

LISTING OF CLAIMS

The following is a copy of Applicants' claims that identifies language being added with underlining ("____") and language being deleted with strikethrough ("~~—~~"), as is applicable:

1. (Currently Amended) A method for determining the authenticity of an object, the method comprising the steps of:
 - receiving an authentication code,
 - determining if particles are distributed within the object in a three-dimensional pattern,
 - determining the positions of particles distributed in the object,
 - using the determination of the positions to provide a check-code,
 - using the check-code and the authentication-code to determine the authenticity of the object.
2. (Original) The method of claim 1, wherein the positions of the particles are determined using a two-dimensional image of the object.
3. (Previously Presented) The method of claim 1, the determination if the particles are distributed in a three-dimensional pattern comprising the steps of:
 - acquiring of a first image of the object with a first angle of illumination,
 - acquiring a second image of the object with a second angle of illumination,
 - combining the first and second images,
 - determining if a geometrical artefact is present in the combined images.
4. (Previously Presented) The method of claim 1, wherein the determination if the particles are distributed in a three-dimensional pattern is made by determining if the object is reflective.

5. (Original) The method of claim 4, wherein it is determined whether the object is reflective by acquiring a first image with diffuse illumination of the object and acquiring a second image with direct illumination of the object and comparing a brightness of the object in the first and second images.
6. (Previously Presented) The method of claim 1, the determination if the particles are distributed in a three-dimensional pattern comprising:
 - illuminating the object with diffuse, white light,
 - detecting light reflected from the object and light transmitted through the object, and
 - determining, if the reflected light and the transmitted light have complementary colours.
7. (Previously Presented) The method of claim 1, further comprising:
 - acquiring an image of the object in a read position,
 - determining a dislocation of the read position with respect to a reference position by detecting marker positions in the image, and
 - performing a projective transformation of the image for compensation of the dislocation.
8. (Previously Presented) The method of claim 1, the check code being provided by:
 - determining the positions of the particles,
 - using the positions to provide the check code.
9. (Original) The method of claim 8, wherein the positions of the particles are determined using a two-dimensional image of the object and wherein the check code is provided by encoding of the positions.
10. (Original) The method of claim 9, further comprising determining a polynomial based on the positions, wherein the encoding of the positions is performed by dividing the polynomial by a generator polynomial.

11. (Original) The method of claim 10, wherein the polynomial is determined by sorting the positions using a sorting criterion and using the sorted positions to obtain the polynomial.
12. (Original) The method of claim 11, wherein the sorting criterion is applied to first coordinate values of the positions, and wherein only the second coordinate values of the sorted positions are used to obtain the polynomial.
13. (Original) The method of claim 12, wherein the polynomial is determined by shifting the second coordinate values by a pre-determined number of bit positions and by concatenating most significant bits of the shifted coordinate values in the order as determined by the sorting of the positions.
14. (Previously Presented) The method of claim 1, further comprising providing position data descriptive of the determined positions, and wherein the check-code is provided by encoding the position data by means of a hashing method.
15. (Currently Amended) An authentication device comprising:
 - means for determining the positions of particles distributed within an object in a three-dimensional pattern,
 - means for determining if particles are distributed within the object in three dimensions,
 - means for encoding the determined positions to provide a check-code,
 - means for entering an authentication code,
 - means for determining the authenticity of the object based on the check-code and the authentication code.
16. (Original) The authentication device of claim 15, wherein the means for determining the positions of the particles is adapted to determine the positions in two dimensions.

17. (Previously Presented) The authentication device of claim 15, wherein the means for determining if the particles are distributed in three dimensions is adapted to determine if the object is reflective.
18. (Previously Presented) The authentication device claim 15, the means for determining the positions of particles comprising image processing means adapted to perform a projective transformation of an image in order to compensate for a dislocation of the image with respect to a reference position.
19. (Original) The authentication device of claim 18, the image processing means being adapted to determine the dislocation by determining of marker positions in the image.
20. (Currently Amended) A card reader for authenticating a customer card, the customer card having an authentication label carrying a three-dimensional pattern of randomly distributed particles, the card reader comprising:
 - apparatus for determining if the particles are distributed within the object in three dimensions and for determining the positions of particles,
 - an encoder for encoding of the determined positions to provide a check-code,
 - an interface for receiving an authentication code,
 - a processor for determining the authenticity of the object based on the check-code and the authentication code.

21. (Currently Amended) An electronic device for reading a data carrier, the data carrier having a copy protection label, the copy protection label carrying a three-dimensional pattern of distributed particles, the electronic device comprising:
- an optical sensor for determining if the particles are distributed within the copy protection label in three dimensions and for determining the positions of particles,
 - an encoder for encoding of the determined positions to provide a check-code,
 - an interface for receiving an authentication code,
 - a processor for determining the authenticity of the object based on the check-code and the authentication code.
22. (Currently Amended) An electronic device for authentication of an object comprising:
- an apparatus for determining if the object has a three-dimensional pattern of distributed particles,
 - a measurement component for determining the positions of particles,
 - an encoding apparatus for encoding the determined positions to provide a check-code,
 - an interface for receiving an authentication code,
 - a processor for determining the authenticity of the object based on the check-code and the authentication code.
23. (Original) The electronic device of claim 22, the measurement component comprising an image processing component.
24. (Previously Presented) The electronic device of claim 22, the measurement component operable to determine the positions in two dimensions.
25. (Previously Presented) The electronic device of claim 22, the apparatus being adapted to determine if the object is reflective.

26. (Previously Presented) The electronic device of claim 22, the apparatus being operable to
- illuminate the object with diffuse, white light,
 - detect light reflected from the object and light transmitted through the object, and
 - determine if the reflected light and the transmitted light have complementary colours.
27. (Previously Presented) The electronic device of claim 22, further comprising:
- an image acquisition apparatus for acquiring an image of the object in a read position,
 - an image processing apparatus for determining a dislocation of the read position with respect to a reference position by detecting marker positions in the image and for performing a projective transformation of the image for compensation of the dislocation.
28. (Previously Presented) The electronic device of claim 22, wherein the measurement component is adapted to determine the positions of the particles using a two-dimensional image of the object and the encoding apparatus being adapted to provide the check code by encoding the positions.
29. (Previously Presented) The electronic device of claim 28, the encoding apparatus operable to determine a polynomial based on the positions, wherein the encoding of the positions is performed by dividing the polynomial by a generator polynomial.